

Analysis of the Applicability of Reconfigurable Computers in Satellite Telemetry Data Processing

Kenneth B. Winiecki, Jr.

Lockheed Martin Space Mission Systems & Services

Marco A. Figueiredo

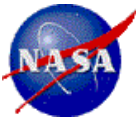
Stinger Ghaffarian Technologies, Inc.

Terry L. Graessle

Lockheed Martin Space Mission Systems & Services

Parminder S. Ghuman

National Aeronautics and Space Administration



Goddard Space Flight Center
Microelectronics and Signal Processing Branch

Photonics East

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Adaptive Scientific Data Processing

Analysis of the Applicability of Reconfigurable Computers in Satellite Telemetry Data Processing



Overview

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- Goal
- Background: A NASA Processing Challenge
 - remote-sensing satellite telemetry data processing
 - the EOS-AM1 spacecraft and MODIS instrument
- Tasks
 - code and hardware selection
 - implementation and results
- Observations
- Conclusions
- For Further Information



Goal

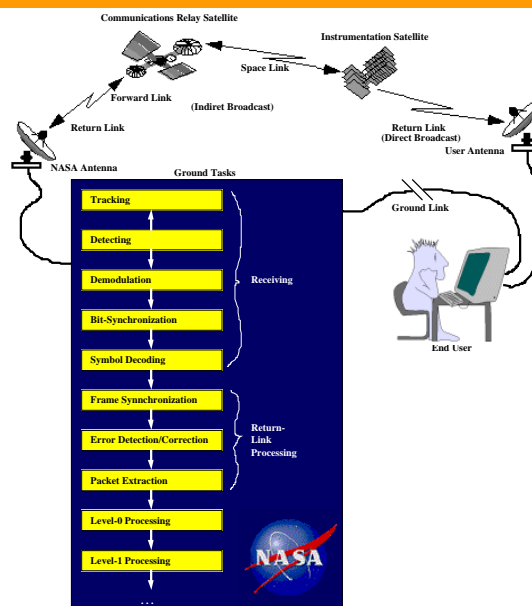
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Examine the utility of applying commercial, off-the-shelf (COTS) reconfigurable computing technology and tools to NASA telemetry data processing within a short (6-month) timeframe.



Remote-Sensing Satellite Telemetry

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Ground-Based Processing



- Receiving
 - tracking, detection, demodulation, bit-synchronization, symbol-decoding
 - well-accommodated in real-time by software and special-purpose hardware
- Return-Link Processing
 - frame-synchronization, error detection/correction, packet extraction
 - well-accommodated in real-time by software and special-purpose hardware



Ground-Based Processing (cont'd)



- Level-0 Processing
 - packet stream separation and reconstruction
 - performed in batch-mode by software
 - » mission-specific: not suitable for special-purpose hardware
 - » highly I/O-bound: not suitable for reconfigurable computing
- Level-1 Processing
 - data stream (image) reconstruction, geolocation, calibration
 - performed in batch-mode by software
 - » instrument-specific: not suitable for special-purpose hardware
 - » some compute-bound tasks suitable for reconfigurable computing



Ground-Based Processing (cont'd)

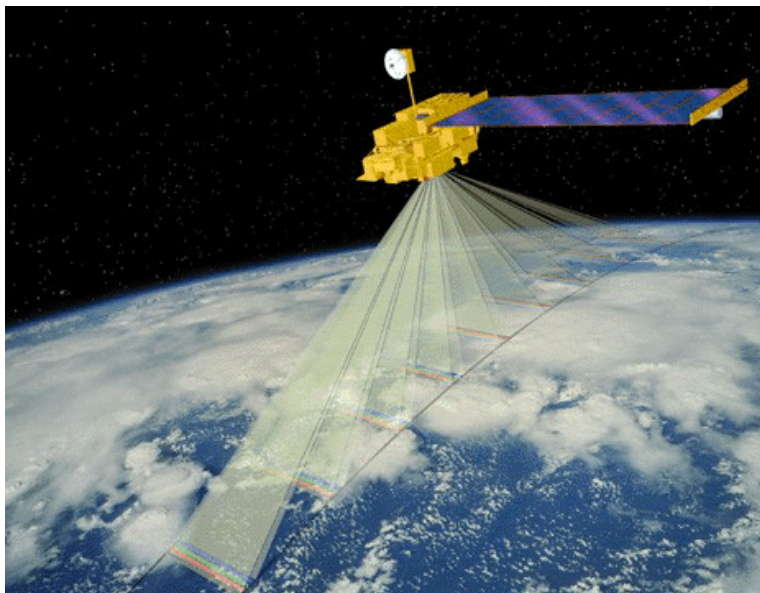
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- Level-2 through Level-N Processing
 - data interpretation, data product generation
 - performed in batch-mode by software
 - » end-user-specific: not suitable for special-purpose hardware
 - » highly compute-bound: suitable for reconfigurable computing



EOS-AM1 Spacecraft with MODIS Instrument

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EOS-AM1 Spacecraft



EOS-AM1: Earth-Observing System Ante-Meridian 1

- launch scheduled for May 1999
- will generate 1 TB (terabyte = 10^{12} bytes) of telemetry data per day
- will double the current NASA earth-science data in 5 months
- will generate 2 PB (petabyte = 10^{15} bytes) of data over its 6-year life
- platform for 5 instruments
 - » Advanced Spaceborne Thermal Emission and Reflection Radiometer (ASTER)
 - » Clouds and the Earth's Radiant Energy System (CERES)
 - » Multi-angle Imaging Spectroradiometer (MISR)
 - » Moderate-Resolution Imaging Spectroradiometer (MODIS)
 - » Measurements of Pollution in the Troposphere (MOPITT)



MODIS Instrument



MODIS: Moderate-Resolution Imaging Spectroradiometer

- scans Earth every 1.447 s, covers the entire surface every 2 days
- each scan contains 36 Earth-view images, one for each of 36 distinct bands of the electromagnetic spectrum from far-infrared through visible, plus a small number of calibration-source-view images
- each Earth-view image is 2200 km long and varies from 10 km wide in the middle to 25 km wide at the ends
- images range from 1354 x 10 pixels (1000 m resolution) to 5416 x 40 pixels (250 m resolution); over 1 M pixels per scan
- all pixel values are 12 bits



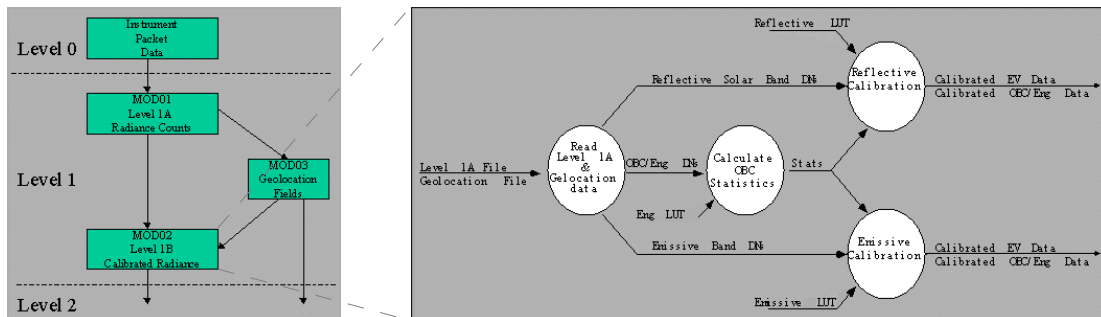
Tasks

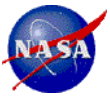


- Study existing code and select fragment to accelerate
- Survey COTS technology and select hardware and development tools
- Design, implement and test a hardware-accelerated version of the code
- Evaluate and demonstrate the solution



MODIS Level-1 Processing





Code Selection



- Level-1: the most universal processing level containing suitably compute-bound tasks
- Level-1B: the most compute-bound Level-1 code module
- Reflective Calibration: the most compute bound Level-1B task, and the largest task that was estimated could be accommodated with the given resources



Hardware Selection



- SGI Origin 200 Server: lowest-cost SGI with PCI bus (existing code written in C for SGI Challenge)
- Annapolis Microsystems' WildForce PCI Reconfigurable Computer: contains 180k gates





Implementation



- Used FPGA logic design tools from Xilinx and Synopsys, and designed only in VHDL
- Pipelined architecture produced one result per 30 MHz clock cycle
- Designed a fixed-point implementation of the floating-point algorithm from the code
- Development details contained in “Adaptive Scientific Data Processing – Fall 1997 Report” available on-line (reference on last page)



Results



```

-----
Initializing software-based L1A-to-L1B program...
Total program time:          49.26 s
Reflective_Cal time:         16.51 s
-----
Initializing FPGA-based L1A-to-L1B program...
Total program time:          39.45 s
Reflective_Cal time:          1.78 s
-----
Software-based Reflective_Cal fraction:  33.52 %
FPGA-based Reflective_Cal fraction:       4.50 %
Speed multiple:                      9.28 X
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```

- Test data set contains 10 scans
- Reflective Calibration processing time dropped 89%, running at more than 9 times the original speed
- Reflective Calibration portion of total processing time dropped 87%, thus ceasing to be a bottleneck



Observations



- Application of RC requires hardware and software engineering skills – i.e., computer engineers
- The ideal RC development tool should accommodate the computer engineer by integrating:
 - design specification in a high-level graphical/symbolic language instead of hardware symbols or hardware description languages
 - partitioning of a design among devices and systems
 - design of configuration overlays (for dynamic reconfiguration)
 - implementation
 - testing and analysis



Observations (cont'd)



- For high-bandwidth host-platform-driven applications, RC products must provide a host interface and driver design which avoids I/O bottleneck
- RC products ought to provide more forward-compatibility to accommodate FPGA product evolution



Observations *(cont'd)*



- 1997 RC technology offered 36 k gates per FPGA device and 40 MHz clock speeds; 1998: 85 k gates, 50 MHz; 1999: 1 M gates?...
- “Reconfigurable computing (RC) is the smallest segment of the FPGA market, but has exhibited sustained growth and is recognized as having the greatest potential”



Conclusions



- Demonstrated nearly an order-of-magnitude improvement in processing speed on one NASA telemetry data processing task in a relatively short time using COTS RC technology and tools
- Indicated that great potential value exists in RC to NASA processing needs
- RC technology seems to be “ripe” for some tasks, still “green” for others



Conclusions (cont'd)

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- Enormous room for improvement exists in RC development tools, RC design, and FPGA design
- Several efforts are underway to address RC application obstacles, funded by the Defense Advanced Research Projects Agency (DARPA) Adaptive Computing Systems study
- The ASDP group at NASA GSFC provides an interface between NASA RC efforts and the research community



For Further Information

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Visit the ASDP Website: <http://fpga.gsfc.nasa.gov/>

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